

# UNIQUE APPLICATION OF MACHINE VISION IN FUTURE AUTOMATED IMMUNOASSAY SYSTEMS

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<b>CKGROUND</b> Inventional automated clinical diagnostic	SAMPLE VOLUME MONITORING METHODS	SAMPLE VOLUME MONITORING RESULTS	PARTICLE RETENTION MONITORING METHODS	PARTICLE RETENTION MONITORING RESULTS
ing systems have various process monitoring ctions (e.g. optical sensors, pressure sensors, mistors, etc). These monitors check the grity of instrument function, but most of those s are limited to indirect sensing and do not ectly monitor the critical elements of correct ay processing. This study examines the use of ew tool, machine vision, to directly monitor	<ul> <li>Purpose:</li> <li>Camera at precise pipettor is used to detect tip presence/absence through all positions of the instrument and measure sample volume aspirated and dispensed</li> <li>Camera can tell software to flag samples out of</li> </ul>	<ul> <li>Linear correlation plot across 4 instruments at different volumes (n = 24; 6 reps per volume) for non dilution and dilutions</li> <li>Camera Volume, µL vs. Color Volume, µL</li> </ul>	<ul> <li>Purpose:</li> <li>Camera at Wash Wheel is used to measure particle presence/absence and can be used as a service test to measure concentration.</li> <li>Particle concentration is a function of both pack fill and instrument (damaged magnetization, too much aspiration, misalignment)</li> </ul>	<ul> <li>The bivariate fit between camera predicted %Conc and spectrophotometer predicted %Conc is linear with a strong correlation</li> <li>The mean variance across the range is 2.2 %CV for the camera and 1.5%CV for the spectrophotometer.</li> </ul>
	volume specification (kinks in tubing, pump/valve failures, tip alignment) or if tip presence/absence is	100-		Bivariate Fit of Camera By Spectrophotometer Predicted Conc % 160

critical assay processing steps.

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The purpose of this poster is to describe the methods and results of the following machine vision applications:

- 1. Sample volume monitoring: image and software algorithms measure the distance from bottom of tip to sample meniscus, using pixels, then convert measurement to volume
- 2. Total reaction volume monitoring: image and software algorithms measure the distance from bottom of vessel to reaction meniscus, using pixels, then convert measurement to volume
- 3. Particle retention monitoring: image and software algorithms execute measurement of gray-scale gradient and convert to particle concentration
- 4. Residual volume monitoring: image and software algorithms execute pattern matching and convert to residual volume

### **PROBLEM STATMENT**

 When we see erroneous results, the system doesn't really provide information on each process inside





**Purpose:** 

tests can report too low

Technology Used:

for collection

Volume Monitoring

**Experimental Methods:** 

with pre-weighted vessels







## instrument (= black box)

4. Upon collection, vessel concentration was measured on spectrophotometer



RESDUAL VOLUME MONITORING METHODS

residual volume left in vessel after reaction build,

wash of particles, and aspiration of excess fluid

misalignment, obstructed tubing, vacuum failure),

• If residual volume is too high (aspiration probe

• Same camera and setup as used in Reaction

1. Instruments were programmed to inducing an

aspiration failure mode by misalignment of

aspiration probes at different heights and loaded

the camera and vessels were transferred to area

2. At each aspiration height, images were taken by

3. Upon collection, vessel weight after dispense

Camera at Wash Wheel is used to measure

## **RESIDUAL VOLUME** MONITORING RESULTS

#### This study showed that at greater than 15 μL, the camera was able to correctly determine too high volume with 95% accuracy.



# CONCLUSION

Summary of accuracy and capability of the four applications:

Sample volume detection range was demonstrated to be 2 to 100  $\mu$ L with  $\pm$  10% accuracy capability

#### **TOTAL REACTION VOLUME TOTAL REACTION VOLUME MONITORING RESULTS MONITORING METHODS** Load Samples **Purpose:** Linear correlation plot of camera volume vs weighed volume 50 – 250 µL (n=20 per volume) • Camera at Wash Wheel is used to measure substrate dispense volume before incubation and Camera Volume, µL vs. Weighed Volume, µL also assist with service and manufacturing for Aspirate Sample volume checks of pumps on the instrument If substrate volume is too low, test can report too low. Volume delivery of reagent and wash pumps Add Reagents out of specification (kinked tubing, pump/valve failure, obstruction) can also impact test results Incubate Monochrome Camera **Technology Used:** - 1280x960, 130in Wash CMOS, 40 FPS with (separate Bound/Free) a 6.2mm lens Red Backlight Read Backlight Camera

Report out



## **Experimental Methods:**

- Camera was calibrated on three instruments to convert pixel to µL
- Instruments were programmed to deliver 50 250 µL of Wash Buffer II solution and loaded with pre-weighed vessels
- 3. After each dispense and mix, images were taken by the camera and vessels were transferred to area for collection
- 4. Upon collection, vessel weight after dispense was measured
- Actual volume ((post-fluid weight pre-fluid weight)/density) was determined after measurements



150

Weighed Volume, µL

200

100

250

was measured
 Actual volume ((post-fluid weight – pre-fluid weight)/density) was determined after measurements
 Normal Residual Volume >15 µL Residual Volume
 Normal Residual Volume 
 15 µL Residual Volume
 Pade
 Pade
 This for a volume

2 to 100 µL with  $\pm$  10% accuracy capability

2. Reaction volume detection range was demonstrated to be 50 to 250  $\mu$ L with ± 10% accuracy capability

 Residual volume detection was demonstrated with a minimum volume of 15 μL capability

Particle retention range of 40-100% retention was demonstrated with  $\pm$  5% accuracy capability

This study confirms the performance of machine vision for direct measurement of various sample reaction volumes. Proactive and direct assessment will potentially permit future immunoassay systems to notify users of processing errors, permitting earlier detection and resolution, and lowering risk that erroneous but believable results will be reported.

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